Abstract — This paper will discuss the origins of MESFET distortion in passive control applications, such as single transistor switch and reflective attenuator circuits. The discussion is based on a lumped element equivalent circuit model and is limited to applications where the MESFET is operating in its conducting state. In switch circuits, the analysis indicates that distortion may be reduced by the use of MESFET's with pinch off voltages in the 2–3 V range and with large open channel current capacities. In attenuators, the analysis shows extreme variations in the level of distortion over a relatively narrow range of attenuation levels. Distortion in the case of the reflective attenuator may be reduced by the use of MESFET's with small open channel current capacities.

I. INTRODUCTION

GALLIUM arsenide (GaAs) metal–semiconductor field effect transistors (MESFET's) offer significant advantages over conventional p-i-n diodes in many radio frequency (RF) and microwave switch and control applications. These advantages include low bias power consumption, the inherent bias isolation of the MESFET, and easy incorporation into monolithic circuits. The MESFET, however, has a specific nonlinear current–voltage characteristic. Thus, there will be harmonically related signals generated by the device when used as a control element. The interest in the distortion generated by MESFET control devices has become more significant recently with the increased use of monolithic MESFET control circuits in RF and microwave systems. In these applications, particularly in sensitive receivers where multiple signals are simultaneously received, the generation of in-band intermodulation signals can seriously affect receiver sensitivity. Similar concerns may be applied to phase shifter and signal routing applications.

A study by Gutmann and Frykholm [1] has shown that the GaAs MESFET exhibits significant nonlinearities at power levels less than 30 dBm. The investigators attribute the resistive nonlinearities to the onset of current saturation in the device. It is also expected that lower levels of nonlinearity will occur in the presaturation or the so-called linear region of operation. These nonlinearities in the conducting state resistance can affect circuit and system parameters such as insertion loss and distortion. More recent studies of GaAs MESFET control circuits by Gutmann and Jain [2], [3] have discussed significant implications in broad-band control circuits using MESFET's due to the gate bias circuitry. This gate bias network is also expected to influence the device and circuit nonlinearities. Absent in any of these works, however, has been a study of those device and circuit parameters that govern the level of distortion in single MESFET switch and control circuits.

This paper analyzes the nonlinear mechanisms of the MESFET in its passive control mode of operation, and equations are developed that will allow designers to predict second- and third-order harmonic and intermodulation products in the conducting state MESFET. The analytic expressions are verified by experimental data.

II. THEORY AND ANALYSIS

A small-signal nonlinear model applicable to RF and microwave frequencies is necessary to determine the distortion characteristics of the MESFET. The basic circuit for the model, shown in Fig. 1, shows a series connected MESFET between a generator \( (V_s, Z_s) \) and a load \( (Z_L) \). Included in the circuit are the gate bias resistance \( (R_g) \) and the gate control voltage \( (V_{ctl}) \). Here, \( Z_L = Z_s = Z_0 \), where \( Z_0 \) is the characteristic impedance of the transmission line, which is assumed to be 50 \( \Omega \). Fig. 2 shows a simple ac equivalent circuit model for the GaAs MESFET in a typical broad-band control application. The nonlinear current–voltage relationship, \( I_{DS} - V_{DS} \), and its relationship to the MESFET channel resistance \( R_{ch} \), needs to be determined to understand the distortion generated in the device. A general expression for the nonlinear \( I_{DS} - V_{DS} \) relationship may be placed in the form of a power series [4]:

\[
I_{DS} = \sum_{n=1}^{\infty} \alpha_n V_{DS}^n
\]

where the \( \alpha_n \) describe the linear \( (n=1) \) and nonlinear \( (n>1) \) behavior of \( I_{DS} \). The \( \alpha_n \) may be found from the results of numerical simulations based on physical models [5], [6], or from closed-form expressions for the drain–source current using the gradual channel-abrupt depletion approxi-
Fig. 2. The ac equivalent circuit of a MESFET used as a broad-band semiconductor control circuit element.

Fig. 3. Second-order intercept point (IP2) plotted versus pinch off voltage \( V_p \) with the open channel current term \( I_p \) as a parameter. The term \( y \) is assumed to be unity.

Closed-form expressions for the \( \alpha_n \) may be found by using a closed-form expression for the \( I_{DS} - V_{DS} \) characteristic, but now including the effects of the gate bias circuit through (2). Assuming uniform channel doping, use of the gradual channel approximation [7]-[9] and (2) allows one to write \( I_{DS} \) as

\[
I_{DS} = I_p \left[ \frac{3V_{DS}}{V_p} - 2 \left( \frac{V + (1 + y)V_{DS}}{V_p} \right)^{1.5} + 2 \left( \frac{V + yV_{DS}}{V_p} \right)^{1.5} \right]^{1/2}
\]

where \( \gamma = V_{GS}/V_{DS} \) (eq. (2)). \( I_p \) is related to the open channel current, \( V_p \) is the pinch off voltage, \( V = V_p - V_{GS} \), \( V_b \) is the built-in junction potential, and \( V_{DS} \) is the dc gate bias voltage. The expression for \( I_{DS} \) in (3) is valid for \( V_{DS} \) less than the saturation voltage \( V_{DSAT} \). This constraint limits the results of the model to small-signal levels where the peak RF voltage across the drain to source channel is less than \( V_{DSAT} \). Using (3), the first three coefficients (\( \alpha_n \)) of (1) may be written as

\[
\alpha_1 = \frac{3I_p}{V_p} \left( 1 - \sqrt{\frac{V}{V_p}} \right)
\]

\[
\alpha_2 = -\frac{3I_p}{4V_p \sqrt{V_p}} (1 + 2\gamma)
\]

\[
\alpha_3 = \frac{I_p}{8(VV_p)^{1.5}} (1 + 3\gamma + 3\gamma^2)
\]

where \( y \) is a function of frequency (eq. (2)). Note that the channel resistance \( R_{ch} \) is the linear term in (1), \( 1/\alpha_1 \).

The form for the nonlinear GaAs MESFET current given in (1) is applicable to any circuit containing one or more devices. A discussion of the distortion in single GaAs MESFET attenuators and switches (in the conducting state) in the presence of a single-tone RF signal follows. The discussion will be limited to second- and third-order distortion, but can be extended to higher order.

The single figure of merit commonly used as a measure of distortion is called the intercept point [11]. The intercept point is an extrapolation of the distortion power to the power level of the drive signal, assuming no compression of the drive signal. It is a fictitious power level, but provides a useful number from which distortion at any drive power may be derived [12]. For the single MESFET circuit shown in Fig. 1, the second (IP2) and third (IP3) order load intercept points may be written as:

\[
IP2 = \frac{\alpha_2^2 Z_0}{2\alpha_2^2} (1 + 2Z_0\alpha_1)^2
\]

and

\[
IP3 = \frac{\alpha_2^3 Z_0}{2\alpha_3} (1 + 2Z_0\alpha_1).
\]

A. Switches

For switch circuits where \( R_{ch} \) is significantly less than \( Z_0 \), IP2 and IP3 may be written as

\[
IP2 = \frac{2592Z_0^2V_{th}V_p^3}{V_p^2} \left( 1 - \sqrt{V_{th}/V_p} \right)^6 / \left| 1 + 2\gamma \right|^2
\]

and

\[
IP3 = \frac{648Z_0^3V_{th}^{3/2}V_p^4}{V_p^{3/2}} \left( 1 - \sqrt{V_{th}/V_p} \right)^4 / \left| 1 + 3\gamma + 3\gamma^2 \right|. \]

Figs. 3 and 4 show IP2 and IP3 plotted versus pinch off voltage \( V_p \) with the open channel current term \( I_p \) as a
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Fig. 4. Third-order intercept point (IP3) plotted versus pinch off voltage \( V_D \) with the open channel current term \( I_p \) as a parameter. The term \( \gamma \) is assumed to be unity.

Fig. 5. Frequency dependence of the second- and third-order intercept points (IP2 and IP3) in a series connected switch. The MESFET exhibits a pinch off voltage of 2.5 V and an open channel current term of 200 mA. A gate resistance of 1 k\( \Omega \) and a gate capacitance of 0.5 pF are used.

parameter for frequencies much greater than the gate circuit time constant (\( \gamma = 1 \)). Note that there is a peak in the intercept point for pinch off voltages in the range of 2–3 V. The decrease in intercept point for pinch off voltages below approximately 2 V is due to the lowered value of \( V_{DSAT} \) in the device, with the resulting nonlinearities caused by operation near the onset of saturation [1]. Also, the intercept point increases with the open channel current term, \( I_p \), and hence the intercept point, may be increased in a circuit by increasing the channel height or width, a condition consistent with improved power handling, switch \( Q \), and conducting state resistance [1], [2], [13]. The distortion characteristics of the p-i-n diode exhibit a similar improvement with reduced forward bias resistance [12].

The frequency dependence of IP2 and IP3 is illustrated in Fig. 5 for a MESFET with a pinch off voltage of 2.5 V and an open channel current term of 200 mA, where the intercept point is plotted versus frequency. In this example, a gate resistance \( R_G \) of 1 k\( \Omega \) and gate capacitance \( C_G \) of 0.5 pF are used. Note that there is a 20 dB increase in IP2 from its low frequency value. The rapid change in intercept point occurs in the vicinity of \( 1/2 \pi R_G C_G \).

Fig. 6. Second- and third-order intercept point (IP2 and IP3, respectively) plotted versus attenuation (\( A \)) for a MESFET with a pinch off voltage of 2.5 V and an open channel current term of 200 mA. The frequency of operation is \( 1/2 \pi R_G C_G \).

B. Attenuators

The identical circuit topology shown in Fig. 1 can be used as a reflective attenuator. In this case, the conducting state resistance \( R_{ch} \) is controlled by the gate bias voltage \( (V_{GSO}) \). If the level of attenuation is defined as

\[
A = \left( \frac{2Z_0}{R_{ch} + 2Z_0} \right)^2
\]

then IP2 and IP3 for the series reflective MESFET attenuator may be written as

\[
\begin{align*}
IP2 &= \frac{A^3 V_p^2}{18 Z_0^3 I_p^2 (1 - \sqrt{A})^2} (V_{bi} - V_{GSO}) / \|l + 2\gamma l^2 (9a) \\
IP3 &= \frac{A^3/2 V_p^{3/2}}{2Z_0^2 (1 - \sqrt{A})^4 I_p} (V_{bi} - V_{GSO})^{3/2} / \|l + 3\gamma + 3\gamma^2 l.
\end{align*}
\]

Here, improvements in attenuator distortion for a given \( V_{GSO} \) may be observed with MESFET's of low current handling capacity (small \( I_p \)). In the attenuator, relatively large values of conducting state resistance (up to several hundred \( \Omega \)) may be required. The larger conducting state resistances may be achieved with lower channel dopings, narrower gate widths, and/or thinner channels, all yielding lower values of \( I_p \) and hence improved attenuator distortion performance. Fig. 6 shows IP2 and IP3 versus attenuation level (\( A \)) for a MESFET with pinch off voltage of 2.5 V and an open channel current term of 200 mA. Note the extreme range of intercept point from 0 to 10 dB attenuation. The low intercept point at the higher levels of attenuation can complicate the design of single MESFET low distortion attenuators.

III. EXPERIMENTAL RESULTS

Second- and third-order distortion measurements were performed using a commercial GaAs MESFET as the control element. This device had measured values of pinch off voltage and open channel current of 2.0 V and 150 mA, respectively. Gate bias was applied through a 1 k\( \Omega \) resistor and the power available from the 50 \( \Omega \) source was kept less than 0 dBm to keep the device out of saturation. The value
of gate capacitance $C_G$ was obtained from the manufacturer's specifications for the MESFET. The distortion test set and measurement techniques were similar to one previously described [12]. For the MESFET operating as a switch in its conducting state (zero gate–source voltage), IP2 was measured from frequencies of 20 to 700 MHz. These measured results are illustrated in Fig. 7, with (7a) plotted for comparison. At low frequencies, the increased distortion (low distortion intercept point) is caused by the MESFET being driven closer to saturation (and the resulting nonlinear operation) during the positive RF swing. As the frequency is increased beyond $1/2\pi R_G C_G$, the floating gate condition reduces the magnitude of $V_{GS}$, allowing more linear operation and an increase in the intercept point.

The distortion performance in a series reflective attenuator was also measured. As the dc gate–source voltage $V_{GS0}$ approaches $V_p$, the MESFET channel is almost completely pinched off. This results in a large value of $R_{ds}$ and hence a high circuit attenuation ($A$). This same operating point, however, also coincides with operation near the MESFET saturation point, a strongly nonlinear region of operation [1], [2]. The result is an increased level of distortion (a lowered intercept point) with increasing circuit attenuation. Figs. 8 and 9 show measured second- and third-order intercept point data plotted versus attenuation level at 410 MHz. Calculated second- and third-order intercept points using (9a) and (9b) are plotted in Figs. 8 and 9 for comparison. Note that for levels of attenuation greater than approximately 3 dB, IP3 is greater than IP2. This crossover attenuation level is a function of both $I_p$ and $V_p$. The experimental data shown in Figs. 8 and 9 verify the large variation in intercept point in single MESFET attenuators.

Fig. 10 shows experimental measurements of IP2 versus frequency at a specific level of attenuation, with (9a) plotted for comparison. As in the switch case, IP2 shows an increase with frequency, with the greatest variation in the vicinity of $F_p$. However, the degree of increase in intercept point is smaller, only about 8 dBm at the 4 dB attenuation level. This variation of intercept with frequency will decrease even further at the highest levels of attenuation.

IV. Conclusions

The results of a nonlinear analysis have been used in determining the level of distortion generated by the MESFET in RF and microwave control applications. The fundamental conclusion reached is that distortion in MESFET control circuits is directly related to the pinch off
voltage and open channel current capacity. The results, applied to series connected MESFET switches and attenuators, show good agreement with experimental measurements and indicate that \( V_p \) and \( I_p \) affect distortion performance. In a MESFET switch, where the MESFET operates with zero dc gate voltage, large \( I_p \) MESFET's will show lower levels of distortion. A peak in the intercept point occurs for those MESFET's with pinch off voltages in the 2–3 V range. In a MESFET attenuator, there is a wide variation in distortion levels over a 10 dB range of attenuation. The distortion level may be minimized by reducing the open channel current capacity in this application. This reduction in \( I_p \) will, however, influence the minimum attenuation level obtainable in the attenuator circuit. In all cases, the distortion is the highest at low frequencies, lowering at frequencies significantly above the gate bias circuit cut off frequency, \( 1/2\pi R_c C_C \). The analytic expressions derived will now allow circuit designers to predict distortion levels in single MESFET control circuits. These expressions will also enable the device designer to modify the MESFET design for specific distortion requirements.

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REFERENCES


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